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SAC CONTRAIL FORMATION STUDY

by

Captain Brian M. Bjornson



MAY 1992

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13. Abstract: This report documents the results of a study that compares the Appleman contrail forecasting method used at the Air Force Global Weather Central (AFGWC) with the SAC method using pilot report (PIREP) data collected by SAC/DOW between March 1990 and July 1991. The study resulted in development of two other contrail forecasting techniques. The first (ETACFCST) was developed using discriminant analysis schemes to obtain "best fit" curves of contrail formation as a function of altitude and temperature, or altitude, temperature, and vertical motion. Statistics showed ETACFCST to be better than either the Appleman or SAC contrail prediction curves. But another technique developed near the end of the study incorporated aircraft engine type as a factor for the first time. The new engine-specific contrail forecasting technique is recommended as a replacement for the Appleman method used at AFGWC.
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PREFACE

This report documents the results of USAFETAC Project 910548, performed for SAC/DOW by USAFETAC's Operations Applications Development section (DNO). Capt Brian M. Bjornson was the writer/analyst.

When SAC/DO identified a weakness in forecasting contrails, SAC/DOW asked USAFETAC for help; specifically, to compare the Appleman method used at the Air Force Global Weather Central (AFGWC) with the SAC/DOW contrail prediction curves, using PIREP data that had been collected by SAC/DOW between March 1990 and July 1991.

In addition to making the comparison requested above, USAFETAC used the SAC/DOW PIREP data to develop a new contrail forecasting technique, called "ETACFCST." Discriminant analysis schemes were used to obtain "best-fit" curves of contrail formation as a function of altitude and temperature, or altitude, temperature, and vertical motion. Statistics showed the new method to be better than either the Appleman or SAC/DOW contrail prediction curves above and below 40,000 feet. Later in the study, Capt Jeffery L. Peters (SAC/DOW) modified the SAC/DOW contrail prediction curve to include an aircraft engine "fuel-to-air" ratio. USAFETAC then used discriminant analysis techniques to determine the best-fit curve of contrail formation as a function of *aircraft engine type*. These algorithms proved superior to the ETACFCST algorithm both above and below 40,000 feet.

USAFETAC therefore recommends that the ETACFCST contrail algorithms, modified to include an aircraft engine type factor, replace the Appleman technique as the AWS contrail prediction algorithm used to forecast contrails.

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1. INTRODUCTION

1.1 Background. In 1989, SAC/DO found a problem with Air Weather Service (AWS) contrail forecasting in that the Appleman contrail forecasting algorithm used by the Air Force Global Weather Central (AFGWC) provided an unacceptable contrail detection probability. AFGWC's inability to forecast contrails to an acceptable degree of accuracy was thought to unnecessarily expose high-flying aircraft to detection. After several other inconclusive studies, SAC/DOW asked USAFETAC (in May 1991) to compare the Appleman and SAC/DOW contrail prediction curves, using a new SAC-provided PIREP database containing 6,815 PIREPS collected by SAC aircrews. Using the new database, which had less bias than the one provided in 1989, USAFETAC developed a new contrail forecasting technique by assuming that the critical temperature for forecasting contrail formation is a function of flight level (or pressure) and vertical motion.

1.2 Related Studies. In 1953, Herbert Appleman constructed curves showing the critical temperature for contrail formation as a function of pressure, relative humidity (RH), and the amount of air entrained into aircraft exhaust, regardless of aircraft type, fuel, or power settings. But since RH values from radiosonde reports are often suspect (especially at low temperatures), AFGWC uses RH assumptions in the Appleman technique--this will be discussed later. Appleman concluded that in a dry environment, contrails form at very low temperatures, whereas in a more humid environment, they can form at higher temperatures. More recent work in contrail forecasting is documented in USAFETAC/PR-90/003, *SAC Contrail Forecasting Algorithm Validation Study*, by Major Walter F. Miller (1990). Miller used an older database of 463 PIREPS collected by SAC aircrews between 1984 and 1987. He evaluated the SAC/DOW contrail forecasting algorithm (which is pressure

independent) and compared it with three RH assumptions using Appleman's algorithm. He found that TROPFCST (an Appleman algorithm in which RH is determined using AFGWC RH assumptions) had a slightly higher contrail forecasting skill than the SAC/DOW algorithm. However, Miller points out that the PIREP dataset used in his study was biased in that 90% of the PIREPS included contrail reports. As a result, the data favored a pessimistic contrail algorithm and overforecasted contrails. Miller's study showed the need for acquiring a database with a balanced number of contrail and no-contrail observations. See Section 2, "Data."

1.3 Methodology. The project was divided into several parts:

- Validate temperature data in the SAC PIREP database with High-Resolution Analysis System (HIRAS) temperature data.
- Calculate vertical velocity from HIRAS data using the kinematic method described in AWS/TR-83/001 and use it to quantify vertical velocity from the SAC PIREP database.
- Provide statistical analyses of the original SAC PIREP database (PIREP temperature and vertical motion) and the quality-controlled SAC PIREP database (HIRAS temperature and vertical motion).
- Develop a new contrail forecasting technique.

We used the original SAC/DOW PIREP data and verified it with HIRAS data. We developed algorithms to forecast contrails based on temperature, flight level, and vertical motion at the PIREP location. Finally, comparative statistics for the Appleman, SAC/DOW, and USAFETAC contrail prediction curves were tabulated. Algorithm limitations, such as in their application to certain types of aircraft and engines, were worked out later in the project; see 3.4 and 4.9.

1.4 Results. Study results are given in three parts:

- Results for contrail formation *at or below* 40,000 feet. Below 40,000 feet, ETACFCST had better skill and a higher probability of contrail detection than Appleman.
- Results for contrail formation *above* 40,000 feet. Above 40,000 feet, ETACFCST had better skill and a lower false alarm rate than Appleman, but offered a lower probability of contrail detection.
- Results for contrail formation based on aircraft engine type.

1.5 Recommendations. Based on the results, we recommend that the algorithms in Appendix D, modified to include aircraft engine type as a factor, replace the Appleman contrail forecasting technique now in use at AFGWC.

2. DATA

2.1 PIREP Database Contents and Limitations. The SAC PIREP database contained 6,815 PIREPS collected by SAC aircrews between 8 March 1990 and 18 July 1991. Each PIREP was composed of the observation number, date, time, latitude and longitude, flight level, contrail formation (yes/no), temperature, sign of vertical motion at the PIREP level, and results (hit/miss) of the SAC/DOW and Appleman techniques. SAC/DOW estimated the sign (+/-) of the vertical motion by examining 300-mb constant pressure analyses. Upward motion was assumed at all levels between the base of a trough and the apex of the upstream ridge; downward motion was assumed between the apex of a ridge and the base of the upstream trough. According to SAC/DOW, some PIREPS above 40,000 feet may contain biased reports of "non-contrails." Several crews reported no contrails at their flight levels above 40,000 feet. However, crews at lower altitudes reported seeing thin contrails from the higher aircraft. The crews at the higher altitudes were apparently unable to see their own contrails, possibly because of glare. The new database, then, may contain erroneous "no-contrail" reports above 40,000 feet.

2.1.1 Dependent Data. About 80% of the PIREPs (5,464 of 6,815) were kept for a dependent dataset. Nearly 3% (137) of the 5,464 had missing or incorrect dates, times, or flight levels; this left 5,327 useable observations in the dependent dataset. More than 80% (4,294) of the 5,327 were at or below 40,000 feet, and 26% (1,110) of these reported contrails. Above 40,000 feet, more than 60% (626 of 1,033) contained contrail reports. The 1,033 PIREPs from above 40,000 feet contained missing latitude and longitude data and also lacked estimates of the vertical motion sign since vertical motion above 40,000 feet is close to zero (it is assumed to be zero at about 75 mb).

Figure 1 shows the locations of more than 95% of the dependent data at or below 40,000 feet. Dependent data above 40,000 feet couldn't be plotted because of missing latitude and longitude values.

2.1.2 Independent Data. 1,351 of the 6,815 PIREPs were chosen at random for an independent dataset; after QC, the number was reduced to 1,341. About 83% (1,110) of the 1,341 were at or below 40,000 feet; 231 were above 40,000 feet. More than 29% of the PIREPs (325 of 1,110) at or below 40,000 feet contained contrail reports. Above 40,000 feet, 71% (165 of 231) reported contrails. Figure 2 shows the locations for more than 95% of the independent data at or below 40,000 feet. Independent data above 40,000 feet couldn't be plotted because of missing latitude and longitude values.

2.2 HIRAS Data. The High Resolution Analysis System (HIRAS) used in the Advanced Weather Analysis and Prediction System (AWAPS) at AFGWC was originally designed to provide improved data for computerized flight plans. Essentially, HIRAS provides only a coarse approximation of the atmosphere. It is optimized for large-scale upper-air flow, not for smaller scale synoptic and mesoscale patterns. It produces global upper-air analyses archived on a 2.5 by 2.5 degree latitude/longitude grid. Data for mandatory levels between the surface and 10 mb can be obtained. The HIRAS model uses observations from land stations, ships, buoys, aircraft, RAOBs, PIBALS, rocketsondes, and satellites. HIRAS variables used in this study were temperature, pressure, u- and v-components of the wind, and tropopause height and pressure. An error field that gives an estimate of the error for each variable at all grid points is carried with HIRAS (see AWS/TN-86/001 for a detailed description of AWAPS).

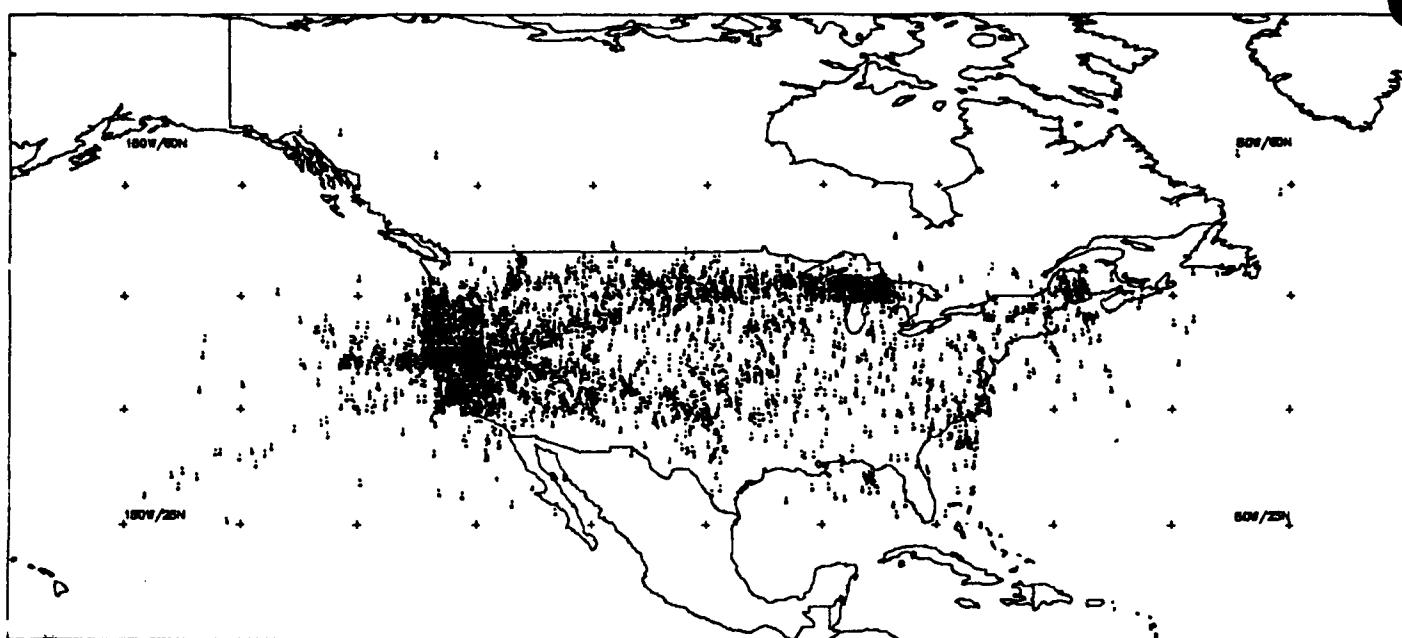


Figure 1. Location of over 95 percent of the *dependent* data at/below 40,000 feet.

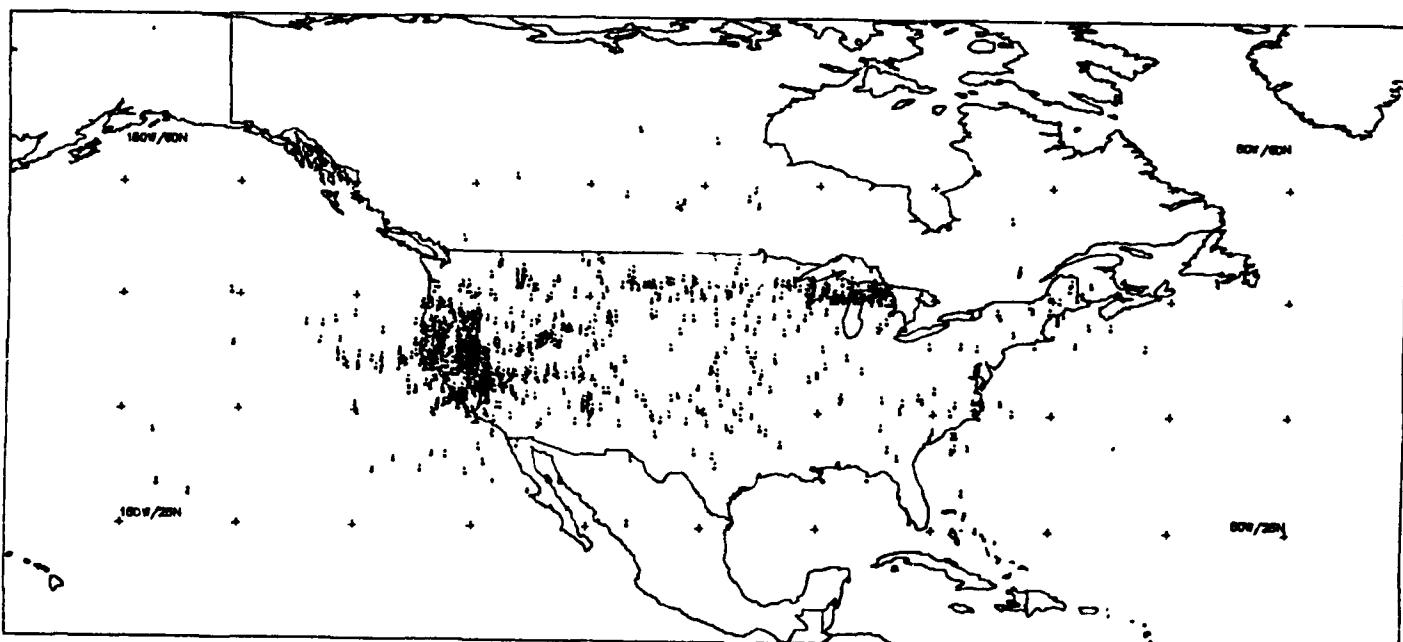


Figure 2. Location of over 95 percent of the *independent* data at/below 40,000 feet.

3. METHODOLOGY

3.1 Calculating Temperature and Temperature Error. Software was developed to calculate temperature (and temperature error) at the PIREP location using HIRAS data.

3.1.1 Ensuring Consistency Between

PIREP and HIRAS Data. I/J latitude and longitude values in HIRAS were converted to the nearest half degree. Flight levels from the SAC PIREP database, in hundreds of feet (Z_F), were converted to meters (Z_M) (Equation 1) and then to pressure (p , in mb) (Equation 2 or 3), as shown below:

$$Z_M = \frac{(Z_F \times 100)}{3.281} \quad (1)$$

If Z_M is less than or equal to 11,000 meters, then:

$$p = 1013.25 \left[1 - \left(\frac{Z_M}{44330.77} \right) \right]^{5.26} \quad (2)$$

If the height is between 11,000 and 20,000 meters, then:

$$p = \frac{226.32}{e^{\left[\frac{(Z_M - 11000)}{6341.62} \right]}} \quad (3)$$

3.1.2 Estimating HIRAS Temperatures Between Data Points.

The horizontal bilinear interpolation equation shown below (from AWS/TR-83/001, Equations 4-9) was applied three times. Temperatures (in degrees Celsius) were interpolated to the PIREP location for the standard pressure level above and below each PIREP; that is, if a PIREP was recorded at 350 mb, temperatures (T , Equation 4) were determined at 300 and 400 mb).

$$T = T_i + \left[\frac{(T_{i+1} - T_i) \times (S - X_i)}{X_{i+1} - X_i} \right] \quad (4)$$

where:

T is the temperature at the required point

T_i is the temperature at grid point i

T_{i+1} is the temperature at grid point $i+1$

X_i and X_{i+1} are distances (meters) between the grid points and an arbitrary point

S is the distance of the required point from the arbitrary point (depending on location of PIREP)

S_1 is distance from point A along line AB until it intersects the horizontal line extending from the PIREP location (point P).

T is the temperature at a distance S_1

X_{i+1} and S are defined relative to X_i ($X_i=0$) and are dependent upon their latitude.

Since the distance between each degree of longitude varies depending on location, the Clarke spheroid of 1866 (Smithsonian, 1984) was used to determine the length of 1 degree of the meridian, depending on the latitude.

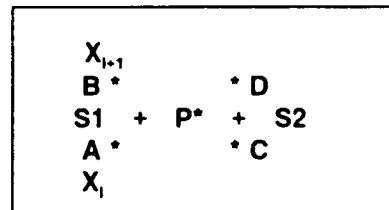


Figure 3. Horizontal bilinear interpolator diagram.

The value of temperature at S_2 is obtained using C as i and D as $i+1$ and Equation 4. Using calculations of temperature at S_1 and S_2 , Equation 5 was used to calculate the temperature at the latitude and longitude position of each PIREP (T_p) at the standard levels above and below each PIREP:

$$T_p = T_{s1} + \left[\frac{(T_{s2} - T_{s1}) \times (P - S_1)}{S_2 - S_1} \right] \quad (5)$$

where P is the distance from S_1 to point P and S_2 is the distance from S_1 .

3.1.3 Determining Temperature at PIREP Pressure Level. A vertical log-pressure interpolator (Equation 6) was used to determine temperature (T) at the pressure level (P) of each PIREP (AWS/TR-83/001, Equations 4-9).

$$T = T_i + \left[\frac{(T_{i+1} - T_i) \times (\ln p - \ln p_i)}{\ln p_{i+1} - \ln p_i} \right] \quad (6)$$

where:

T is the temperature at the pressure level (p) where the PIREP was made

T_i is the temperature at pressure p_i

T_{i+1} is the temperature at pressure p_{i+1} .

Temperatures at 400 and 300 mb (T_i and T_{i+1} , respectively) were taken directly from bi-linear horizontal interpolation results (see 3.1.2); p is also known. See Figure 4.

3.1.4 Determining Temperatures. The root mean square error for HIRAS temperature is 2-3° C. An error field carried with HIRAS gives an estimate of temperature error for each point. PIREP temperatures were compared to HIRAS temperatures. When the absolute value of their difference was greater than the absolute value of

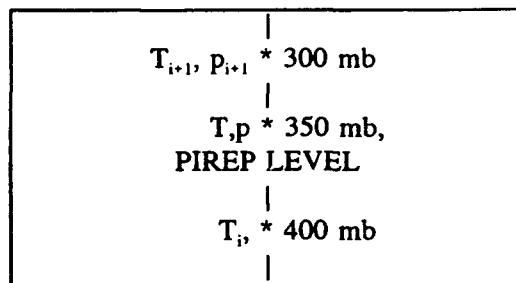


Figure 4. Vertical log-pressure interpolator diagram.

the error plus 1° C, the data was flagged (i.e., identified as HIRAS temperatures in the dataset) and comparison statistics were generated. Original PIREP temperatures and calculated HIRAS temperatures were included in the final dataset.

3.2 Calculating Vertical Velocity from HIRAS Data. We developed software to calculate the vertical velocity at the PIREP location (using HIRAS data) by applying the kinematic method described in AWS/TR-83/001. Both HIRAS vertical velocity and PIREP (original) vertical velocity were included in the final dataset. According to Duffield and Nystrom (1983), the kinematic method (based on the continuity equation) for estimating vertical velocity is preferred over the adiabatic method or omega equation. After the first integration of the continuity equation from the surface to pressure level p_i , the new lower boundary value for vertical velocity (w) becomes the bottom value for the next integration. This results in a problem because of the inaccuracy of the winds, together with the cumulative error in the integration processes. To eliminate the problem, Nystrom suggested starting the integration process at 75 mb (where $w = 0 \text{ ms}^{-1}$) and working downward through the atmosphere.

3.2.1 Vertical Velocity Calculation Between Pressure Levels. Equation 7 was used to calculate vertical velocity between each standard level from 75 mb to the surface (standard levels are 100, 150, 200, 250, 300, 400, 500, 700, 850, and 1,000 mb). (Note: The

equation below was derived from Equations 4-7, AWS/TR-83/001. Lt Col Nystrom, co-author of

that publication, modified the equation for use in this study).

$$w_{k-1} = \left[\frac{(\varrho_k \times w_k)}{\varrho_{k-1}} \right] - \left\{ \left[\frac{1}{(\varrho_{k-1} \times d)} \right] \times \left[\left(\frac{d_x u}{d} \right) + \left(\frac{d_y v}{d} \right) \right] \times [100(p_k - p_{k-1})] \right\} \quad (7)$$

where:

w_{k-1} is the vertical velocity (ms^{-1}) half a level below the standard level

w_k is the vertical velocity half a level above the standard level ($w_k = 0 \text{ ms}^{-1}$ at 75 mb)

ϱ_k is the density (kgm^{-3}) at level k ($\varrho = (100*p)/RT$)

p is the pressure in mb

T is the temperature K

R (the dry gas constant) is $287 \text{ J}^{\circ}\text{K}^{-1}\text{kg}^{-1}$

ϱ_{k-1} is the density at level $k-1$

g is acceleration due to gravity ($g = 9.81 \text{ ms}^{-2}$)

s'), $d_x u$ (the divergence) is the difference of u (u-comp of horizontal wind, ms^{-1}), linearly interpolated to the center of the north/south line between grid points, in the east/west line

$d_y v$ is the difference of v in the north/south line

d is the distance in meters between grid points and varies depending on latitude location of PIREP

$p_k - p_{k-1}$ is the difference in pressure (mb) between pressure at level k and level $k-1$.

The calculation is started at 75 mb, with w_k assumed to be zero. The divergence terms are calculated from the 100-mb level data to produce the vertical velocity at 125 mb. This process is repeated downward through the atmosphere to the surface.

3.2.2 Vertical Velocity Calculation at the PIREP Pressure Level. A vertical log-pressure interpolator (similar to the one described in 3.1.3) was used to calculate vertical velocity at the pressure level of the PIREP. For example, if a PIREP was taken at 350 mb, vertical velocity at the PIREP location was

determined using a vertical log-pressure interpolator with wind and pressure inputs from 300 and 400 mb. Vertical velocities were quality-controlled to ensure that there were no gross values (in general, values were between -0.08 and +0.08 m/s). Only the sign of the vertical velocity was kept in the final dataset, since actual values were questionable. The sign of the vertical velocities calculated from HIRAS was compared with the sign of the original vertical velocity. Both dependent and independent datasets used in this study contain vertical velocities calculated from HIRAS and PIREP data.

3.2.3 Vertical Motion-Kinematic Method vs 300-mb Analysis. The success or failure of the kinematic method in providing reliable results depends on how well horizontal winds in HIRAS represent actual atmospheric conditions. HIRAS, unfortunately, describes only the synoptic scale upper-airflow because its resolution is only 2.5 by 2.5 degrees. The kinematic method produces the best results where a dense network of observed winds is available. Whether or not this method is superior to "eyeballing" 300-mb analyses is unknown. Although the resolution on the NGM 300-mb analysis (60 nm) is better than HIRAS, vertical interpolation was not used in the eyeballing process to determine vertical motion at the altitude (pressure) the PIREP was taken. The eyeballing method assumes the sign of the estimated vertical velocity at 300 mb represents the sign of the actual vertical velocity at the PIREP location.

3.3 Statistics. All statistics included in this report were prepared from two combinations of temperature and vertical motion. Data extracted from the final SAC PIREP database.

- PIREP temperature and PIREP vertical motion data (original).
- HIRAS temperature and HIRAS vertical motion data (calculated).

Standardized normal variables (Z test statistics) were computed to determine the equality between the percent frequencies of contrail occurrences using upward and downward motion. If the Z statistic was greater than a certain value, the frequency of contrails associated with upward motion is significantly different from percent frequencies associated with downward motion.

3.3.1 Sensitivity Analyses of Temperature vs Altitude. Each sensitivity analysis gives the number of occurrences/non-occurrences and percent frequency of altitude vs temperature. Temperatures were stratified in 5° C increments; altitude was stratified in 5,000-feet increments.

3.3.2 The USAFETAC Contrail Prediction Curve. A discriminant analysis (DA) scheme was used to obtain a "best-fit" curve (USAFETAC contrail prediction curve) of contrail formation as a function of altitude vs temperature and of altitude vs temperature vs vertical motion. Discriminant analysis involves deriving the linear combination of two or more independent variables that will best discriminate between the categories of the dependent variable (in DA, the dependent variable must be categorical; i.e., yes/no). Discriminant analysis is the appropriate statistical technique for testing the hypothesis that the group means of two or more groups are equal (Hair et. al., 1987). To accomplish this, each independent variable is multiplied by its corresponding weight and their products are added together. The result is a single composite discriminant score for all observations within a particular group. The Fisher discriminant function (Afifi and Clark, 1984) is written:

$$Z = a_1 X_1 + a_2 X_2 \quad (8)$$

where a_1 and a_2 are the discriminant weights, X_1 and X_2 are the independent variables, and Z is the discriminant score. In this study, altitude (PIREP flight level) and temperature are the *independent* variables; contrail (vs no-contrail) formation is the *dependent* variable. A separate DA was completed using dependent data classified by:

- upward motion (data at or below 40,000 feet)
- downward motion (data at or below 40,000 feet)
- all data at or below 40,000 feet (upward, downward, and missing vertical motion)
- all data above 40,000 feet (missing vertical motion)

Separate discriminant analyses were accomplished for PIREP (original) and HIRAS (calculated) data. As requested by the customer, separate discriminant analyses were also completed for each 5,000-foot increment between FL 200 and 400, using HIRAS data. These

results were compared with results obtained by using a single discriminant equation to forecast contrails at or below 40,000 feet.

3.3.3 Tropopause Height and Pressure Data Extracted from HIRAS Database.

This data was needed to estimate relative humidity for use in applying the Appleman and SAC/DOW contrail prediction curves using original and calculated temperature and vertical motion data. In both curves, RH is assumed to be 40% in the troposphere, 70% within 300 meters of the tropopause, and 10% in the stratosphere (see USAFETAC/PR-90/003 for a detailed description of these curves). Contingency tables were created using SAC PIREP data (original PIREP and calculated HIRAS data) and applying the Appleman and SAC/DOW curves. Statistics (described in 3.3.5) generated using the different prediction curves were then compared with statistics applying the USAFETAC contrail prediction curve.

3.3.4 Dependent Data Less Than or Equal to 40,000 Feet

was plotted on scatter diagrams with the Appleman, SAC/DOW, and USAFETAC (ETACFCST) contrail prediction curves overlaid. Twelve diagrams were prepared; six using PIREP (original) data, and six using HIRAS (calculated) data. Each dataset (PIREP, HIRAS) was used to plot data containing records with:

- upward motion only
- downward motion only
- upward, downward, and missing vertical motion (all motions)

The three categories were divided further so that the Appleman and SAC/DOW curves with different RH assumptions could be plotted and analyzed. The customer requested that the Appleman and SAC/DOW curves for 100% RH and for 40% RH be plotted on separate diagrams. Contrail occurrences were denoted by a plus sign; non-occurrences, by a diamond. Because several observations of contrails and

no-contrails were overprinted (hiding multiple observations at a single point), a random number generator was used to add (or subtract) small increments of temperature and altitude from the actual value. Since vertical motion is missing above 40,000 feet, data above 40,000 feet was plotted on scatter diagrams using PIREP data only. Two scatter diagrams were completed with the USAFETAC, Appleman, and SAC/DOW contrail prediction curves overlaid. As requested by the customer, one plot depicted Appleman and SAC/DOW curves assuming 10% RH; the other assumed 100% RH.

3.3.5 Skill Scores.

The Heidke skill score (HSS) was used to assess the skill or accuracy of the results. The equation used is:

$$HSS = \frac{(F - D)}{(T - D)} \quad (9)$$

where F is the number of *correct forecasts*, T is the *total number of forecasts*, and D is the *number of forecasts expected to be correct based on chance*. The equation for D is:

$$D = \frac{[(C_1 \times R_1) + (C_2 \times R_2) + \dots + (C_n \times R_n)]}{T} \quad (10)$$

where:

n is the number of contingencies

C and R are the sums of the columns and rows taken from the contingency table shown in Figure 5

T is the total number of forecasts

The HSS ranges from -1 (no skill) to 1 (total accuracy). In meteorological applications, an HSS between 0.30 and 0.40 is considered satisfactory, and an HSS greater than 0.40 typically indicates good skill. According to Appleman (1960), the HSS does not measure forecasts against a true standard. From Equations 9 and 10, the expected number of correct forecasts based on pure chance depends on the number of forecasts for each category issued. Appleman indicates that the standard

should be independent of forecasts being evaluated, and suggests replacing the variable "D" in Equation 9 with the number of observations in the category that is observed most frequently. His critical skill index (CSI) is given by:

$$CSI = \frac{X}{[X + (T_f - X) + (T_o - X)]} \quad (11)$$

where X is the number of correct forecasts, T_f is the number of event forecasts, and T_o is the total number of event occurrences. Woodcock (1976) stated that the Heidke skill score is "trial-dependent"; that is, any trial in which the events and non-events are not equally represented (e.g., contrail occurrences vs non-occurrences) is biased. Woodcock suggested using Hanssen and Kuipers' (1968) discriminant "V" score:

$$VDS = \frac{AD - BC}{[(A + B) \times (C + D)]} \quad (12)$$

where VDS is the discriminant V-score, ranging from -1 (no skill) to 1 (total accuracy). A , B , C , and D are elements from a "2x2" contingency table shown in Figure 5:

		CONTRAILS	
		FCST NO	FCST YES
OBS NO	A	B	
OBS YES	C	D	

Figure 5. Contingency Table.

According to Woodcock, VDS provides an impartial and satisfactory measure of forecasting accuracy for scientific purposes and should therefore be weighted highest when interpreting results. Goldsmith (1989) recommended using probability of detection (POD), false alarm ratio (FAR), and critical skill index (CSI) to supplement skill scores. POD is the number of correct forecasts of an event divided by the total number of times the event occurred. FAR is the

number of times an event was incorrectly forecast to occur divided by the total number of times the event was forecast. All measures discussed so far are included in Section 4, "Results."

3.3.6 The "p-value" (PVAL) is one of the statistics generated from the "chi-square" test, which is used to determine if the *observed* frequency distributions differ significantly from *expected* frequency distributions (those which result from chance). The chi-square test shows only whether or not two frequency distributions differ significantly from each other. When chi-square is larger than certain limits, the observed frequency distribution is significantly different from the expected distributions (i.e., the results are not by chance). The level of significance, or PVAL, is used to determine the weight of the difference between observed and expected distributions. P-values less than or equal to 0.01 indicate that results are almost certainly significant.

When the p-value is 0.05, there is one chance twenty that the forecast could have been made by chance--this is still considered a reliable result. P-values greater than 0.05 usually indicate that results are *not* significantly different from chance. For this study, p-values less than or equal to 0.05 were considered to indicate statistically significant results.

3.4 Engine-Specific Contrail Forecasting Algorithm. Just before publication of this document, SAC/DOW changed its contrail prediction algorithm to include the fuel-to-air ratio of aircraft engines found in certain SAC aircraft; that is, the algorithms were changed to make contrail forecasting engine-specific. The statistics in Appendix D, Tables 1-5, support the use of engine-specific algorithms for forecasting contrails.

3.4.1 Engine Classification. Engines were classified as "high-bypass" (KC-135R), "low-bypass" (KC-10), or "non-bypass" (KC-135A, B-52G, U-2).

3.4.2 Verification. USAFETAC verified the new engine-specific algorithms using USAFETAC's empirical (discriminant analysis) method for forecasting contrails with PIREP data sorted by aircraft type as follows: KC-135A,

322 PIREPS; KC-135R, 334 PIREPS; B-52G, 340 PIREPS; and U-2, 1,110 PIREPS. Since there was no data available for the KC-10, the low-bypass engine algorithm could not be verified. Statistics based on discriminant analysis techniques were generated and compared with statistics produced using the new SAC/DOW contrail curves based on Applemans's theoretical algorithm--see Figure 4.9.

4. RESULTS.

4.1 HIRAS vs PIREP Temperature.

Calculated HIRAS temperatures replaced original PIREP temperatures in about 60% (2,564 of 4,294) of all dependent observations at or below 40,000 feet. PIREP and HIRAS temperatures were retained for use in separate discriminant analyses and scatter diagrams. HIRAS temperatures could not be determined above 40,000 feet because these PIREPS lacked reports of latitude and longitude necessary for the horizontal and vertical interpolators used to calculate HIRAS temperature at the PIREP level.

4.2 HIRAS vs PIREP Vertical Motion. The sign of the vertical velocity (+/-) between calculated HIRAS velocities and original PIREP velocities differed in nearly 38% (1,615 of 4,294) of all dependent observations at or below 40,000 feet. In 21% (910 of 4,294) of these cases, estimates of upward motion from 300-mb analyses (original data) were calculated as *downward* vertical motion from HIRAS data; more than 16% (705 of 4,294) of downward motion estimates from 300-mb analyses were calculated as *upward* motion from HIRAS. Ninety-two percent (1,480 of 1,615) of HIRAS and PIREP vertical velocity differences occurred when the estimated HIRAS vertical velocity was close to zero (within +/- 0.005 m/s). Both HIRAS and PIREP vertical motions (sign only) were retained for use in separate discriminant analyses and scatter diagrams, which will be discussed later.

4.3 Sensitivity Analyses of Temperature vs Altitude. Tables 1 through 5 depict the number of occurrences/non-occurrences and percent frequency of occurrences/non-occurrences of contrails (above and below 40,000 ft) as a function of temperature and altitude. Tables 1 to 3 show results using PIREP data; Tables 4 and 5 depict results using HIRAS. Regardless of the data used (PIREP or HIRAS), our results support Appleman's theory that the potential for contrails increases as temperature

decreases. Although Appleman considered the effects of relative humidity on contrail formation, he did not analyze the effects of vertical velocity.

4.3.1 PIREP Data At/Below 40,000 Feet.

Z test statistics for PIREP data indicate that differences in frequency of occurrence between upward and downward vertical motion were significantly different (see 4.3.1.2).

4.3.1.1 PIREP Temperatures and All Vertical Motion Data (upward, downward, and missing vertical motion). Contrails occurred in only 27 of 509 (5%) of all observations between FL 200/240, in relatively warm air. Contrail frequency increased to 21% (383 of 1,811) between FL 250/290 and 33% (558 of 1,682) between FL 300 and 340. Between FL 350 and 400, contrail frequency increased to 61% (140 of 230) overall. When temperatures were -50° C or less, contrail frequency increased to over 73% between FL 250 and 340 and to about 77% (109 of 141) between FL 350 and 400. Finally, at the lowest temperatures (less than -55° C), frequency of contrails increased to over 85% (112 of 131) between FL 300 and 400.

4.3.1.2 PIREP Temperatures; Upward Motion (Table 1) vs Downward Motion (Table 2). Between FL 250 and 340, frequency of contrails using upward vertical motion was about twice the frequency for downward motion (29 vs 14% between FL 250 and 290 and 44 vs 22% between FL 300 and 340). Between FL 350 and 400, frequency of contrails was 74% (73 of 99) for upward motion and only 54% (59 of 109) for downward motion. As temperatures decreased to -50° C or below between FL 250 and 340, contrail frequency increased to 83 percent (110 of 132) using upward motion, compared with 63% (89 of 142) using downward motion. At altitudes between FL 350 and 400 with temperatures below -50° C, contrails occurred in 83% (53 of 64) of observations associated with upward motion as compared to 66% (51 of 77) for downward motion.

TABLE 1. Number of occurrences/non-occurrences and percent frequency of occurrences/non-occurrences of contrails at/below 40,000 feet as a function of PIREP temperature, PIREP *upward* vertical motion, and altitude (flight level).

Temp at FLTLVL	200/240 Contrail				250/290 Contrail				300/340 Contrail				350/400 Contrail			
	No	N	%	Yes	No	N	%	Yes	No	N	%	Yes	No	N	%	Yes
-64 to -60	1	100	.	.	6	100	.
-59 to -55	1	5	21	95	6	22	21	78
-54 to -50	3	14	19	86	21	19	88	81	5	17	25	83
-49 to -45	23	28	58	72	77	39	129	61	9	38	15	63
-44 to -40	2	50	2	50	68	44	85	56	154	62	96	38	4	50	4	50
-39 to -35	8	80	2	20	185	81	42	19	160	81	37	19	1	100	.	.
-34 to -30	28	84	2	5	195	86	33	14	62	86	10	14
-29 to -25	41	95	2	5	119	85	21	15	8	89	1	11	1	50	1	50
-24 to -20	65	92	6	8	34	87	5	13
> -20	57	95	3	5	5	100
ALL	202	92	17	8	632	71	264	29	483	56	374	44	26	27	72	73

TABLE 2. Number of occurrences/non-occurrences and percent frequency of occurrences/non-occurrences of contrails at/below 40,000 feet as a function of PIREP temperature, PIREP *downward* vertical motion, and altitude (flight level).

Temp at FLTLVL	200/240 Contrail				250/290 Contrail				300/340 Contrail				350/400 Contrail			
	No	N	%	Yes	No	N	%	Yes	No	N	%	Yes	No	N	%	Yes
-64 to -60	1	33	2	67	1	14	6	86
-59 to -55	1	33	2	67	6	22	21	78	3	10	28	90
-54 to -50	1	100	.	.	4	40	6	60	46	81	66	59	13	83	17	57
-49 to -45	53	67	25	33	148	76	46	28	15	71	6	29
-44 to -40	3	100	.	.	159	80	39	20	260	92	22	8	13	87	2	13
-39 to -35	22	88	3	12	198	93	15	7	92	93	7	7	3	100	.	.
-34 to -30	39	98	1	3	167	92	15	8	37	95	2	5	1	100	.	.
-29 to -25	42	100	.	.	105	95	6	5	1	100
-24 to -20	72	97	2	3	39	91	4	9
> -20	60	97	2	3	2	67	1	3
ALL	239	97	8	3	728	86	113	14	591	78	166	22	49	85	59	55

4.3.2 PIREP Temperature Data Above 40,000 Feet, No Vertical Motion Data Available. As shown in Table 3, frequency of contrails above 40,000 feet was highest (100%, 20 PIREPS) between 410 and 440 feet, but decreased to 75% (501 of 667) between FL 440 and 650. Above FL 650, contrails occurred in

only 30% (104 of 346) of observations even though frequency was near 75% (28 of 37) when temperatures were -70° C or lower. When all flight levels above 40,000 feet were considered, contrails occurred in 92% (327 of 354) of all observations when temperatures were -70° C or less.

TABLE 3. Number of occurrences/non-occurrences and percent frequency of occurrences/non-occurrences of contrails above 40,000 feet as a function of PIREP temperature and altitude (flight level).

Temp at FLTLVL C	410/480 Contrail				450/590 Contrail				500/580 Contrail				550/490 Contrail				600/680 Contrail				650/690 Contrail			
	No		Yes		No		Yes		No		Yes		No		Yes		No		Yes		No		Yes	
	N	S	N	S	N	S	N	S	N	S	N	S	N	S	N	S	N	S	N	S	N	S	N	S
-50	2	100	2	105	1	100
-79 to -75	3	100	1	20	8	80	2	9	61	97	1	100
-78 to -70	2	100	.	.	1	100	.	.	2	100	3	27	8	73	12	5	212	95	9	26	25	74	6	100
-69 to -65	5	100	1	18	6	86	8	84	5	56	96	35	179	65	153	60	60	31	5	6
-58 to -60	6	100	2	29	5	71	1	100	41	87	6	13	72	98	5	6	3	38
-59 to -55	6	100	1	33	2	67	1	100	1	50	1	50	5	61	3	38	.	.
-58 to -50	1	100
ALL	20	100	4	22	14	78	2	22	7	78	8	32	17	58	152	25	463	75	281	70	105	30	.	.

4.3.3 HIRAS Data At/Below 40,000 Feet.

Z test statistics for HIRAS data indicate that differences in frequency of occurrence between upward and downward vertical motion were *not* significantly different, except for results at flight levels between 250 and 290 feet (see 4.3.3.2).

4.3.3.1 HIRAS Temperatures and All Vertical Motion Data.

Results using HIRAS temperatures and all vertical motion data were similar to results using PIREP data (see 4.3.1.1). Contrail frequency increased between 20,000 feet (5%) and 40,000 feet (60%). Frequency of contrails ranged from 72 to 86% between FL 250 and 400 when temperatures were -50° C or less.

4.3.3.2 HIRAS Temperatures; Upward (Table 4) vs Downward (Table 5) Motion.

Although results using either HIRAS or PIREP data coupled with all vertical motions are nearly identical (compare 4.3.1.1 with 4.3.3.1), when HIRAS upward vs downward vertical motion data were compared with PIREP data (see 4.3.1.2), the results were

much different. Between FL 250 and 340, frequency of contrails was 28% (462 of 1,632) using upward vertical motion and 26% (479 of 1,857) using downward motion. Between FL 350/400, frequency of contrails was 64% (81 of 127) for downward motion versus 57% (59 of 103) using upward motion. When PIREP data was used between FL 200 and 400, the frequency of contrails using upward motion was about twice as high as that found when using downward motion (35% vs 18%). However, when HIRAS data is used, frequency using upward motion is 29%, compared to 25% for downward motion. The differences in techniques used to estimate the sign of the vertical velocity is probably the major reason for these differences. Also, the original PIREP database contained 206 records with missing vertical velocity estimates; as a result, there are 206 fewer observations used in the PIREP dataset for comparing upward vs downward vertical motions and their relationship with contrail formation.

TABLE 4. Number of occurrences/non-occurrences and percent frequency of occurrences/non-occurrences of contrails at/below 40,000 feet as a function of HIRAS temperature, HIRAS upward vertical motion, and altitude (flight level).

Temp at FLTLVL	200/240 Contrail				250/290 Contrail				300/340 Contrail				350/400 Contrail			
	No	S	N	S	No	S	N	S	No	S	N	S	No	S	N	S
-69 to -65	1	100
-65 to -60	1	100	.	.	4	100
-59 to -55	3	14	19	86	3	14	18	86
-54 to -50	3	100	25	26	72	74	17	40	26	60
-49 to -45	.	.	2	100	20	32	42	68	122	63	71	37	14	64	8	36
-44 to -40	3	100	.	.	96	62	60	38	197	75	66	25	9	75	3	25
-39 to -35	10	91	1	9	143	81	34	19	164	85	29	15
-34 to -30	27	90	3	10	215	87	33	13	33	83	7	18
-29 to -25	41	100	.	.	117	88	16	12
-24 to -20	54	95	3	5	39	83	8	17
> -20	85	96	4	4
ALL	220	94	13	6	630	76	196	24	544	67	266	33	43	42	59	58

TABLE 5. Number of occurrences/non-occurrences and percent frequency of occurrences/non-occurrences of contrails at/below 40,000 feet as a function of HIRAS temperature, HIRAS downward vertical motion, and altitude (flight level).

Temp at FLTLVL	200/240 Contrail				250/290 Contrail				300/340 Contrail				350/400 Contrail			
	No	S	N	S	No	S	N	S	No	S	N	S	No	S	N	S
-64 to -60	4	100
-59 to -55	8	19	17	81	6	15	33	85
-54 to -50	4	27	11	73	88	34	85	66	15	33	30	67
-49 to -45	33	41	47	59	154	58	112	42	19	61	12	39
-44 to -40	.	.	2	100	143	71	58	29	228	81	52	19	6	86	1	14
-39 to -35	11	85	2	15	212	88	30	12	138	88	19	12
-34 to -30	41	93	3	7	215	89	26	11	16	70	7	30
-29 to -25	44	94	3	6	145	93	11	7
-24 to -20	63	95	3	5	44	92	4	8
> -20	103	99	1	1	2	100
ALL	262	95	14	5	798	81	187	19	580	67	292	33	46	37	80	63

4.4 Discriminant Analyses and Scatter Diagrams. The best-fit curves of contrail formation as functions of temperature vs altitude and of temperature vs altitude vs vertical motion using both PIREP and HIRAS data are described below. Results are given for "at/below 40,000 feet" and "above 40,000 feet." Appendix A compares the skill and accuracy of the SAC/DOW, Appleman, and U...FETAC contrail prediction curves. Scatter diagrams (Figures 6-11) are also shown, with the different prediction curves overlaid (SAC/DOW requested Appleman and SAC/DOW contrail prediction curves be plotted using 40% and 100% RH for data at/below 40,000 feet; RH is assumed equal to 10% and 100% for plots above 40,000 feet).

4.4.1 PIREP Temperature Data At/Below 40,000 Feet. The scatter diagrams in Figures 6 through 11 depict contrail formation as functions of altitude and temperature, or altitude, temperature, and vertical motion, using original PIREP data. SAC/DOW and Appleman curves are plotted assuming either 100 or 40% RH. Associated statistics are provided in Tables A-1 through A-3 in Appendix A. P-values (not shown) indicate statistically significant results, regardless of the type of vertical motion.

4.4.1.1 Upward, Downward, and Missing Vertical Motion (all PIREP data). Scatter diagrams for all PIREPS at/below 40,000 feet are shown in Figures 6 and 7. The Appleman and SAC/DOW

curves with RH = 100% (Figure 6) and RH = 40% (Figure 7) are overlaid. Also shown is the USAFETAC best-fit curve based on the discriminant equation:

$$TCRIT = -28.21 - (0.0391 \times FL) \quad (13)$$

where $TCRIT$ is the flight level temperature ($^{\circ}$ C) and FL is the flight level in hundreds of feet (e.g., 300 = 30,000 feet). If the actual temperature is less than $TCRIT$, contrails are inferred. Statistical results (Appendix A, Table A-1) support the USAFETAC contrail prediction curve (ETACFCST), even though its percent correct (COR) is about 10% lower than for the other curves. All three skill scores (VDS, HSS, CSI) are higher for ETACFCST, especially the discriminant V-score (VDS). Although ETACFCST has a high false alarm rate (FAR), the probability of detection (POD) is considerably higher than Appleman or SAC/DOW. Equation 13, therefore, can be used to forecast contrails based on FL and $TEMPFL$. The chi-square statistical test indicates the model (equation) produces statistically significant results ($PVAL < 0.05$). Figure 7 provides a "quick-look" comparison of the contrail prediction curves assuming 40% RH, which is realistic for the troposphere. Appleman and SAC/DOW curves do not distinguish between contrails and no-contrails well because many actual occurrences of contrails are depicted as non-contrails, resulting in a low POD.

4.4.1.2 Upward Vertical Motion. Scatter diagrams for upward motion PIREPS at/below 40,000 feet are shown in Figures 8 and 9. Appleman and SAC/DOW curves are overlaid with the RH assumption as described in 4.4.1.1. The ETACFCST discriminant curve for forecasting contrails is plotted using the discriminant equation:

$$TCRIT = -24.59 - (0.0495 \times FL) \quad (14)$$

All skill scores for ETACFCST (Table A-2) are satisfactory, and indicate higher skill than Appleman and SAC/DOW curves. POD and COR are excellent for ETACFCST, but the FAR

is over 40%. Results for Appleman are slightly better than results for SAC/DOW.

4.4.1.3 Downward Vertical Motion. Scatter diagrams for downward motion PIREPS at/below 40,000 feet are shown in Figures 10 and 11. Appleman, SAC/DOW, and ETACFCST curves are overlaid. The ETACFCST discriminant equation for forecasting contrails associated with downward motion is shown below:

$$TCRIT = -28.58 - (0.04626 \times FL) \quad (15)$$

Skill scores (Table A-3) show that ETACFCST and Appleman are both skillful in forecasting contrails associated with downward vertical motion. However, nearly twice as many contrails are detected using ETACFCST and Appleman (79 vs 42% POD). Unfortunately, the false alarm rate is twice as high for ETACFCST than for Appleman (67 vs 31%).

4.4.2 PIREP Temperature Data Above 40,000 Feet. The scatter diagrams for all PIREPS above 40,000 feet are shown in Figures 12 and 13. Appleman and SAC/DOW curves assuming 100% and 10% RH are overlaid (Figures 12 and 13, respectively). ETACFCST discriminant curves are plotted based on the equation:

$$TCRIT = -31.59 - (0.0572 \times FL) \quad (16)$$

Statistics (Table a-4) indicate that Appleman and ETACFCST are skillful and fairly accurate. ETACFCST has higher skill (VDS=0.60) and lower FAR (11.6%) than Appleman (VDS=0.47 FAR=23.0) but Appleman has a better POD (91.4 vs 75.4%). The SAC/DOW curve lacks skill mainly because it cannot distinguish between contrails and no-contrails. Equation 16 can be used to forecast contrails based on flight-level and flight-level temperature. If the forecast flight-level temperature is less than $TEMPFL$ as calculated from Equation 16, then contrails should be forecast. The chi-square statistical test indicates that this equation is statistically significant ($PVAL<0.05$). These results indicate

that Equation 16 is reliable for use in predicting contrail formation above 40,000 feet. The discriminant analysis curve (Figure 13) is similar to the Appleman curve, which is considerably warmer (about 3° C) near 41,000 feet and over 4° C warmer at 70,000 feet). Figure 13 also indicates that the Appleman curve does not

distinguish well between contrails and "no contrails," because many actual non-occurrences of contrails are depicted as occurrences. The data does not support the SAC/DOW curve, which indicates that contrails occur when the air temperature is less than or equal to -52° C.

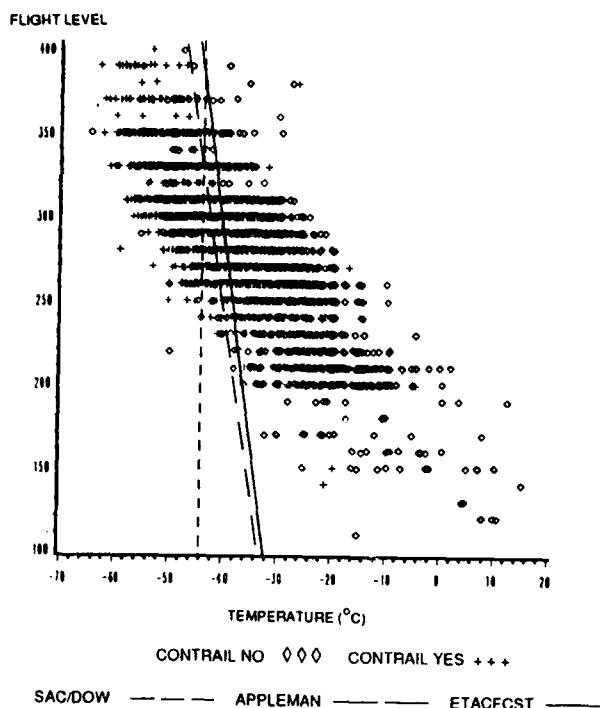


Figure 6. Scatter diagram: All PIREP data at/below 40,000 feet, *all vertical motion data*, $RH=100\%$ for Appleman and SAC/DOW curves.

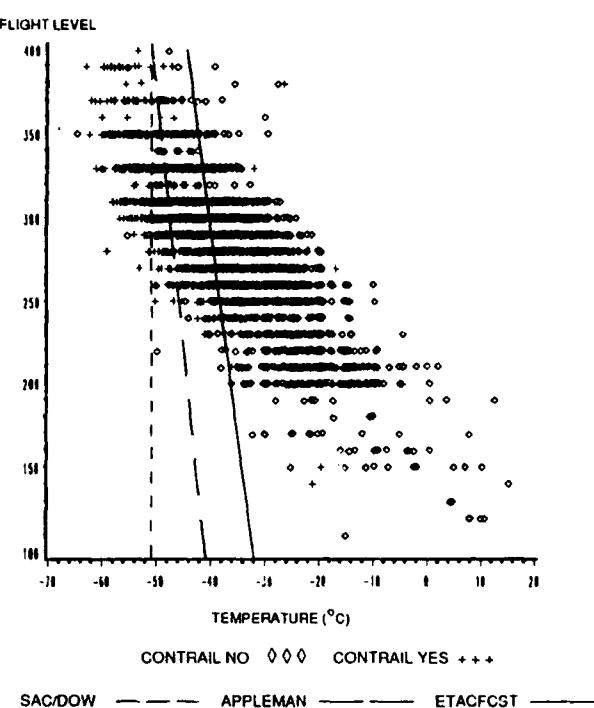


Figure 7. Scatter diagram: All PIREP data at/below 40,000 feet, *all vertical motion data*, $RH=40\%$ for Appleman and SAC/DOW curves.

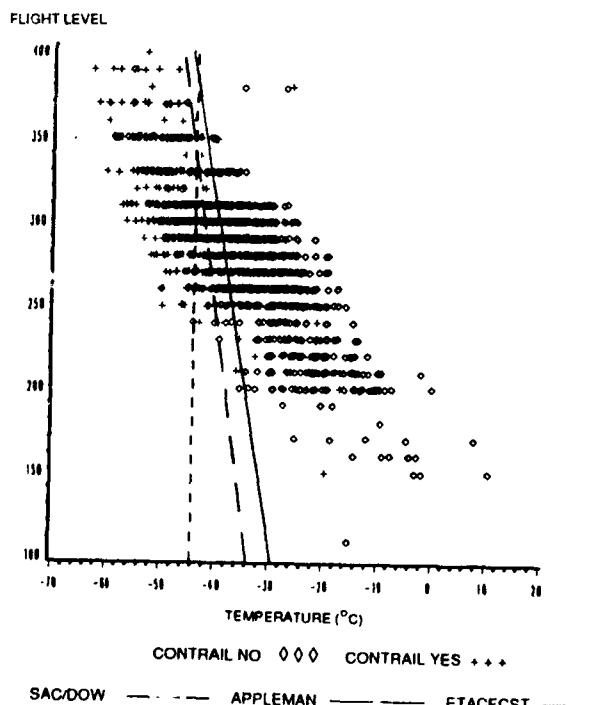


Figure 8. Scatter diagram: All PIREP data at/below 40,000 feet, *upward vertical motion only*, $RH=100\%$ for Appleman and SAC/DOW curves.

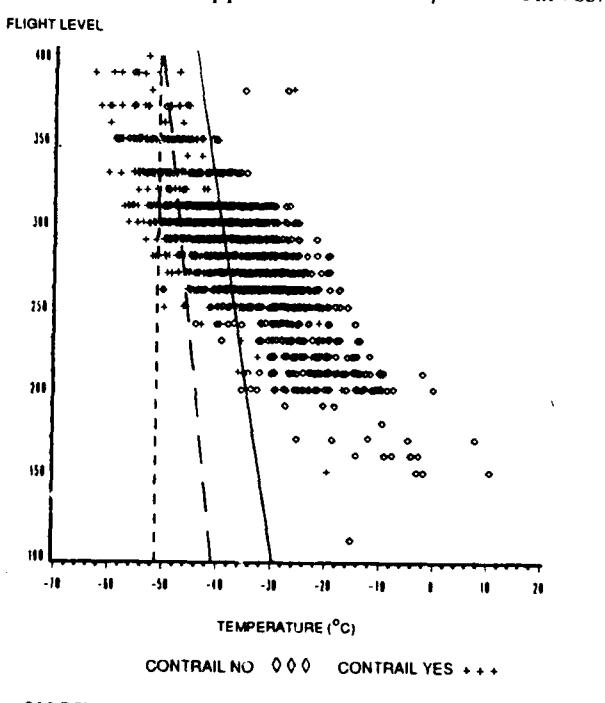


Figure 9. Scatter diagram: All PIREP data at/below 40,000 feet, *upward vertical motion only*, $RH=40\%$ for Appleman and SAC/DOW curves.

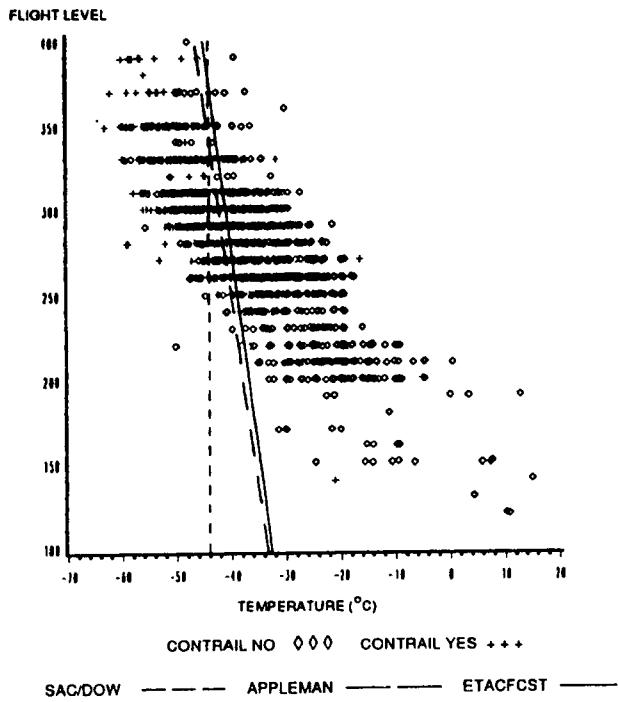


Figure 10. Scatter diagram: All PIREP data at/below 40,000 feet, using *downward vertical motion* only, $RH=100\%$ for Appleman and SAC/DOW curves.

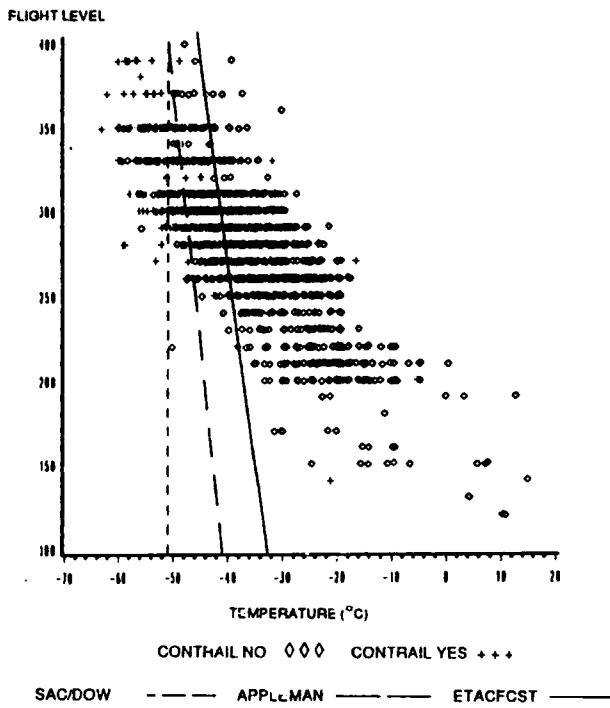


Figure 11. Scatter diagram: All PIREP data at/below 40,000 feet, using *downward vertical motion* only, $RH=40\%$ for Appleman and SAC/DOW curves.

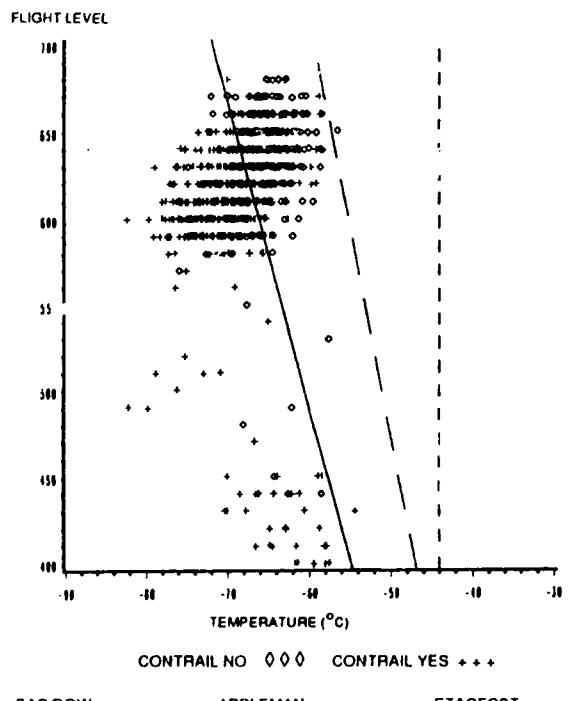


Figure 12. Scatter diagram: All PIREP data above 40,000 feet, $RH=100\%$ for Appleman and SAC/DOW curves.

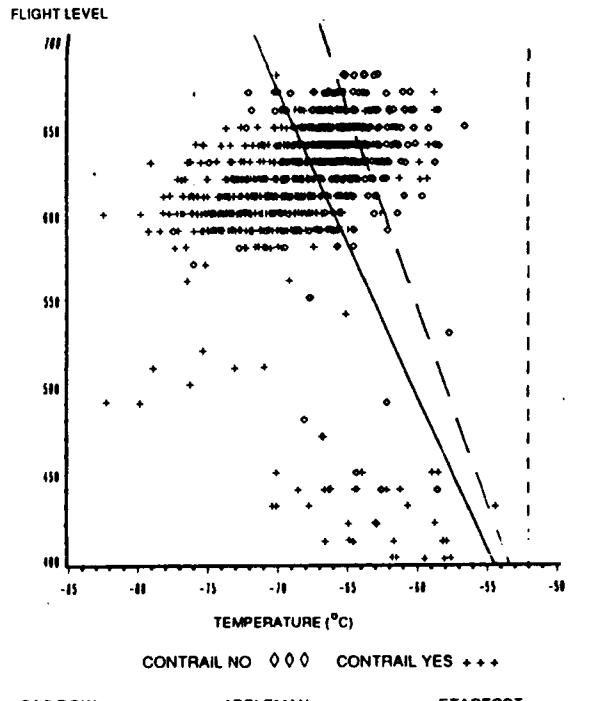


Figure 13. Scatter diagram: All PIREP data above 40,000 feet, $RH=10\%$ for Appleman and SAC/DOW curves.

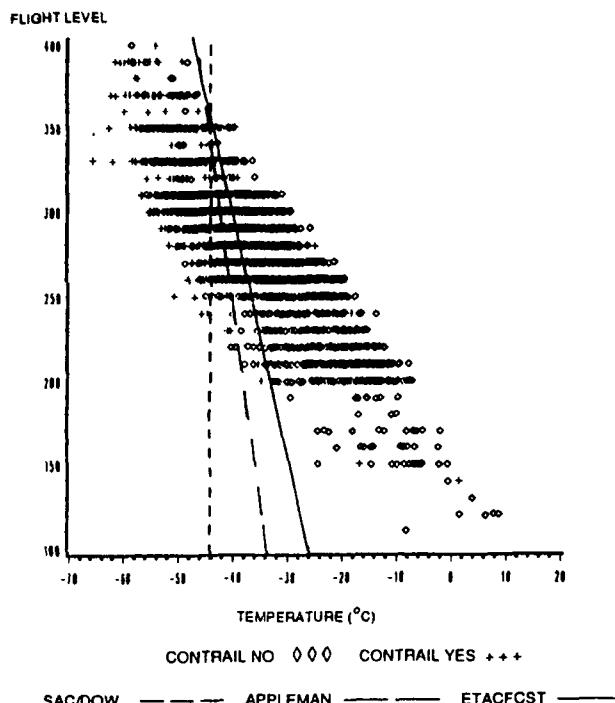


Figure 14. Scatter diagram: All HIRAS data at/below 40,000 feet, using *all vertical motion*, $RH=100\%$ for appleman and SAC/DOW curves.

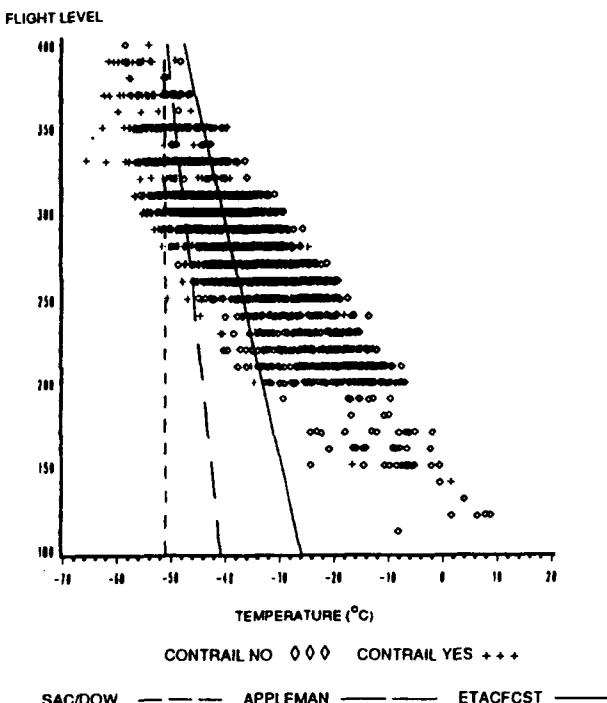


Figure 15. Scatter diagram: All HIRAS data at/below 40,000 feet, using *all vertical motion*, $RH=40\%$ for appleman and SAC/DOW curves.

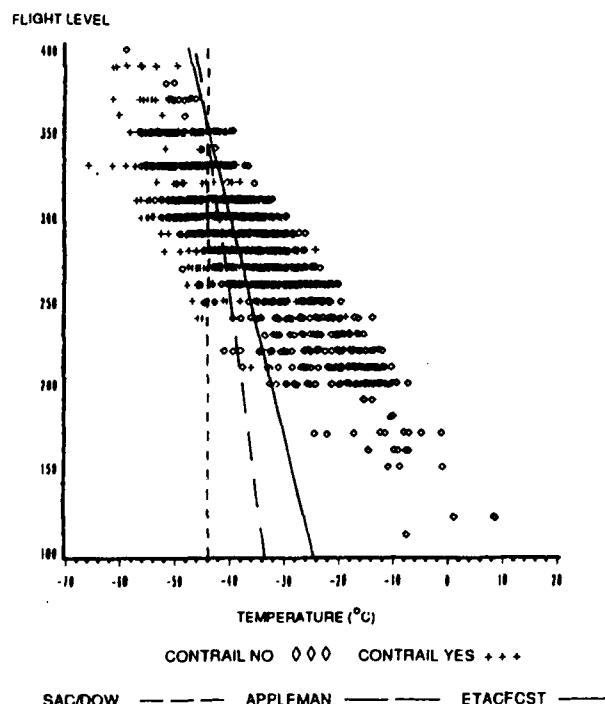


Figure 16. Scatter diagram: All HIRAS data at/below 40,000 feet, using *upward vertical motion only*, $RH=100\%$ for Appleman and SAC/DOW curves.

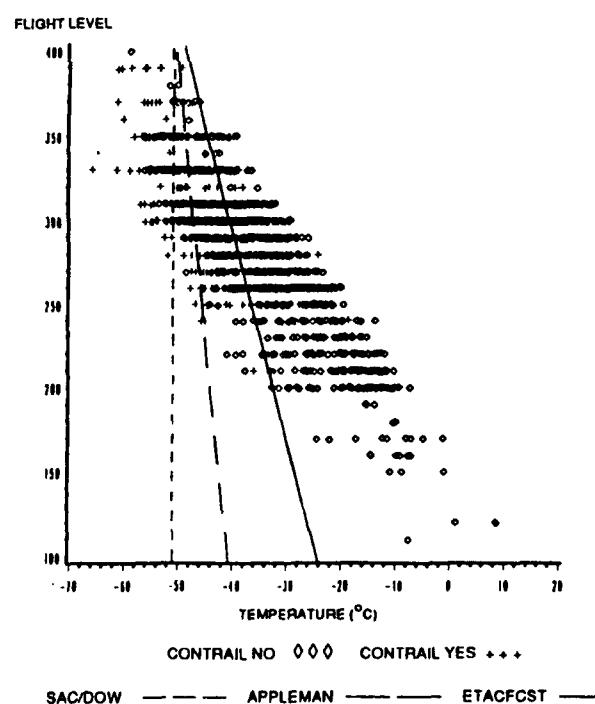


Figure 17. Scatter diagram: All HIRAS data at/below 40,000 feet, using *upward vertical motion only*, $RH=40\%$ for Appleman and SAC/DOW curves.

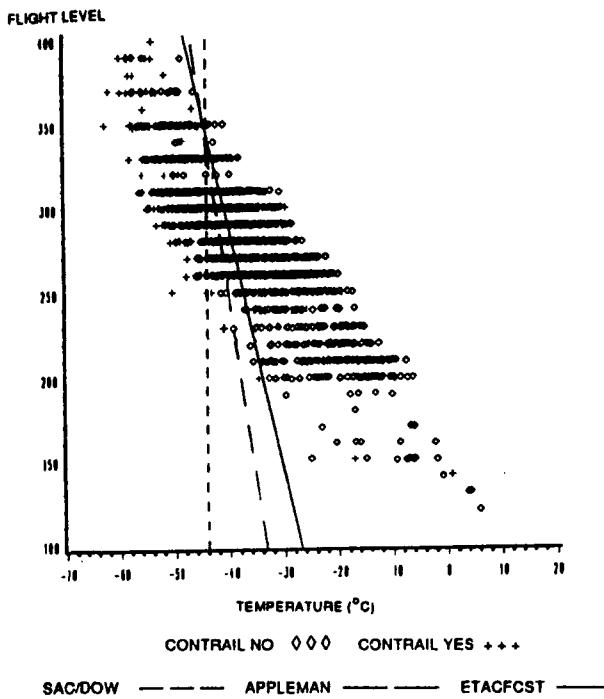


Figure 18. Scatter diagram: All HIRAS data at/below 40,000 feet, using *downward vertical motion only*, RH=100% for Appleman and SAC/DOW curves.

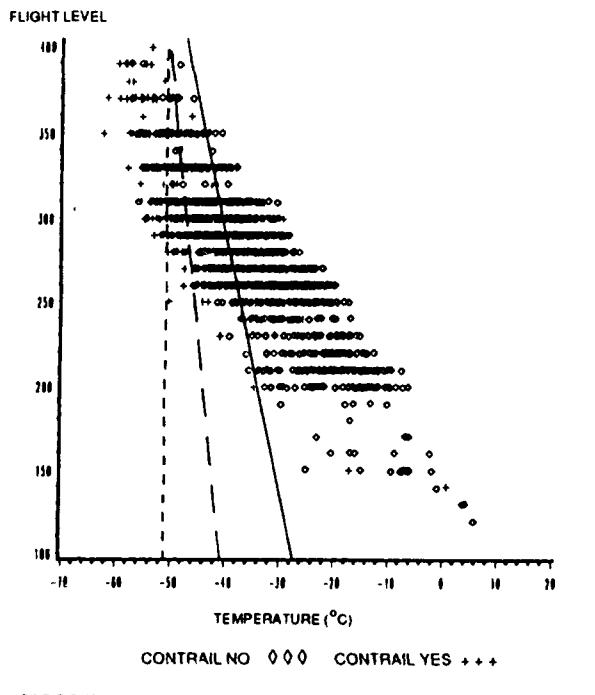


Figure 19. Scatter diagram: All HIRAS data at/below 40,000 feet, using *downward vertical motion only*, RH=40% for Appleman and SAC/DOW curves.

4.4.3 HIRAS Temperature Data At/Below 40,000 Feet. Figures 14 through 19 depict contrails as a function of altitude and temperature or altitude, temperature, and vertical motion using calculated HIRAS data. SAC/DOW and Appleman curves are plotted assuming 100 or 40% RH; ETACFCST curves are also plotted based on the following discriminant equations:

$$TCRIT = -18.90 - (0.0717 \times FL) \quad (17)$$

for HIRAS temperatures and upward/downward vertical motion;

$$TCRIT = -16.32 - (0.0793 \times FL) \quad (18)$$

for HIRAS temperatures and upward motion; and

$$TCRIT = -20.39 - (0.0681 \times FL) \quad (19)$$

for HIRAS temperatures and downward motion. $TCRIT$ and FL represent the temperature ($^{\circ}$ C) and flight level and flight level (hundreds of feet), respectively. Statistical results (Appendix A, Tables A5-A7) using HIRAS are similar (but slightly inferior) to results using original PIREP data. ETACFCST proves to be the best predictor of contrails, regardless of the sign of the vertical motion. POD is considerably higher for ETACFCST than for Appleman or SAC/DOW, but the FAR is also higher. The discriminant V-score indicates moderate skill for ETACFCST and low skill for Appleman and SAC/DOW, regardless of the sign of vertical motion.

4.4.4 HIRAS Data in 5,000- or 6,000-Foot Increments Between FL 200 and 400. HIRAS data was separated into three 5,000-foot bins and one 6,000-foot bin between 20,000 and 40,000 foot by flight level, as shown below:

- FL 200 and 240
- FL 250 and 290
- FL 300 and 340
- FL 350 and 400.

4.4.4.1 Upward/Downward Vertical Motion (All Motions). The discriminant equations (with resulting statistics) using all vertical motion data are shown in Appendix B, Table B-1. The slope of the discriminant curve decreases (becomes more negative) with increasing flight level. Below FL 250, the slope is positive, which indicates that contrail frequency increases with increasing temperature. This finding is not supported by physics or statistics, which indicate poor skill, FAR, and POD. All statistics improve considerably between FL 200 and 240 and between FL 350 and 400. In general, there is some improvement in forecasting contrails using this method (i.e., separate discriminant equation every 5,000 feet) compared to one discriminant curve for all data at/below 40,000 feet (compare Tables A-5 and B-1). Furthermore, this method is slightly better than results obtained when applying the same discriminant curve (Equation 17) for each 5,000-foot increment of data at or below 40,000 feet (compare Table A-5 with Table C-1 of Appendix C). However, this improvement at many layers is a statistical artifact of having fewer data points to fit; i.e., two opposite categorical data points will always produce a perfect discriminant analysis solution.

4.4.4.2 Upward Vertical Motion. The discriminant equations (with statistics) using HIRAS upward motion data are shown in Appendix B, Table B-2. Little, if any, improvement is noted by using separate discriminant equations every 5,000 feet between FL 200 and 400 (Table B-2), compared to using one discriminant equation (Equation 18) for all data at/below 40,000 feet (Table A-6) or applying the same equation (18) to each 5,000-foot increment between FL 200 and 400 (Appendix C, Table C-2). Although skill and POD are slightly lower for each 5,000-foot increment (Table B-2) than for ETACFCST (Table A-6), POD does improve considerably between FL 350 and 400 (Table B-2).

4.4.4.3 Downward Vertical Motion. Table B-3 depicts the discriminant equations and associated statistics using HIRAS downward vertical motion

data. Slopes decrease (become more negative) with increasing flight level up to 34,000 feet, then increase slightly between FL 350 and 400. Statistics show favorable results, especially above FL 300. This method offers some improvement over the use of a single discriminant equation (19) for all data at/below 40,000 feet (compare Tables A-7 and B-3) or over the use of a single equation (19) for data in 5,000-foot increments at/below 40,000 feet (Table C-3). This is especially true above 35,000 feet, where skills are relatively high and the false alarm rate is low.

4.5 Comparison with Data from Previous Study. Data used by Miller (1990) was run through the same software used to create statistics associated with the ETACFCST, SAC/DOW, and Appleman techniques. The data was limited to altitudes of 40,000 feet or less. ETACFCST software was based on discriminant curves using PIREP and HIRAS temperature and all vertical motion data (Equations 13 and 17, respectively). Results for the different curves were unimpressive. Although ETACFCST had a high POD (94% using PIREP data or 88% with HIRAS data) and low FAR (7% using PIREP or HIRAS data), two skill scores indicated little skill ($VDS=0.11$ and 0.03 ; $HSS=0.00$ and 0.03 using PIREP or HIRAS data, respectively). The CSI, however, did indicate high skill ($CSI=0.88$). SAC/DOW and Appleman curves were equally unimpressive. Both had equal or slightly better skill than ETACFCST, but the POD was 10 to 20% less. The poor skill for all the curves is primarily the result of the inability to forecast non-occurrences of contrails.

4.6 ETACFCST Curve Comparison. ETACFCST contrail prediction curves based on original PIREP and calculated HIRAS data were compared for upward, downward, and all vertical motions. Slopes of the discriminant curves were similar (compare slopes in Equations 14 and 17, 15 and 18, 16 and 19). For example, slopes of HIRAS and PIREP upward motion discriminant curves were 0.079 and 0.049, respectively. At 40,000 feet, the critical temperature varies by 2

to 7° C due to the change in slope of the discriminant curves. About 73% (1,524 of 2,093) of the PIREPs associated with upward motion were correctly forecast; 68% (1,361 of 2,002) were correctly forecast using HIRAS data. For downward motion, percent correct was about 69% for both PIREP and HIRAS data. Similarly, results indicate that although HIRAS temperatures replaced PIREP temperatures in about 60% of all dependent observations, there was very little difference in the discriminant curves using HIRAS (or PIREP) temperatures with HIRAS or PIREP vertical motions. For example, comparing results using PIREP temperature and upward vertical motion data with HIRAS temperature and PIREP upward vertical motion data, the slope of the discriminant equation ranged from 0.050 to 0.075, respectively; percent correct differed by less than 1% (only 19 of 2,093 correct forecasts differed). Thus, it appears the biggest changes (although small) in slope (and percent correct) occurs when comparing results from the different methods used to calculate vertical velocity.

4.7 Independent Testing. We kept 1,341 observations for independent testing; 1,110 occurred at/below 40,000 feet, 231 above 40,000 feet. Results of the tests are shown in the tables of Appendices A, B, and C. In general, results support ETACFCST as the most skillful of the three contrail prediction curves. POD, FAR, and COR were similar to results using the dependent data (described above). Based on these results, ETACFCST may be a satisfactory method for predicting contrails at any flight level above 25,000 feet.

4.8 AFGWC Results as Tabulated by SAC/DOW. SAC/DOW provided results of the AFGWC contrail analysis forecast results using the Appleman technique (hit or miss) in the PIREP database. USAFETAC generated and compared statistics using the "hit/miss" data to statistics provided in Table A-1 (see Appleman category in dependent test). In general, statistics were similar. Below 40,000 feet, all three skill scores (VDS, HSS, and CSI) in Table A-1 were

within 0.06 of the skill scores computed using the SAC/DOW provided hit/miss data (e.g., HSS = 0.33 from Table A-1 as compared to 0.31 using AFGWC's hit/miss data). The percent correct was within 1% and the false alarm rate and probability of detection were within 10% of the scores obtained using the SAC/DOW results. Above 40,000 feet, all statistics (Table A-4, Appleman category) were easily within 10% of the statistics calculated using SAC/DOW provided hit/miss data. Our implementation of the Appleman technique, therefore, appears to be consistent with AFGWC.

4.9 Discriminant Analysis Using Engine-Specific Data. The USAFETAC empirical technique for forecasting contrails scored much higher than the new SAC/DOW theoretical technique when using B-52G data (Appendix D, Table D-1) and slightly higher using KC-135R data (Table D-2). There was little difference between the two techniques when using KC-135A (Table D-3) or U-2 data (Table D-4). The USAFETAC technique produced better results than SAC/DOW's, probably because USAFETAC did not assume RH as SAC does. Instead, USAFETAC determines a temperature threshold that indirectly accounts for a mean atmosphere RH profile that supports a slightly moister RH profile than those given by Nieman (1977) and used at AFGWC. The profiles are reasonable (60% RH vs 40% at 25,000 feet and 20% RH vs 10% in the stratosphere).

Discriminant analysis was also used to obtain the best-fit curve for contrail formation for all non-bypass engine data (KC-135A and B-52G data combined). The results (Table D-5) indicate good skill, a high probability of detection, and a low false alarm rate.

Caution: The algorithm based on U-2 data should be applied at altitudes above 40,000 because all the data in the sample were from above 40,000 feet. On the other hand, algorithms developed from KC-135A, KC-135R, and B-52G data should *not* be used to forecast contrails above 40,000 feet because only one

observation in the database was from above that altitude. Since contrails seldom occur between 20,000 and 24,000 feet (they were reported in only 27 of 509 PIREPS in the database), the

algorithms work best between 25,000 and 40,000 feet. Note: these results were not tested using an independent data set.

5. CONCLUSIONS & RECOMMENDATIONS.

5.1 Conclusions. Although HIRAS temperatures replaced PIREP temperatures in about 60% of all dependent observations at/below 40,000 feet, there was very little difference (less than 1% correct), between the discriminant equations and associated statistics using HIRAS or PIREP temperature data with either HIRAS or PIREP vertical motions. Combination algorithms based on USAFETAC's empirical contrail forecasting technique and SAC/DOW's engine classification technique provided better results than either technique used alone. Although Equation 17 (ETACFCST using HIRAS upward/downward vertical motion data) could replace the Appleman algorithm technique as the contrail prediction algorithm used by AFGWC, the engine-specific algorithms are better.

5.1.1 HIRAS and PIREP vertical motion data differed in about 38% of all dependent observations at/below 40,000 feet, even though the methods used to estimate the sign of vertical velocity were different. Over 90% of HIRAS and PIREP vertical velocity differences occurred when the estimated HIRAS vertical velocity was near zero +/- 0.005 ms⁻¹. Regardless of the technique, the slopes of the discriminant equations were similar, with only a 2-5% correct difference.

5.1.2 Contrail frequency using PIREP data increased from about 20% at 25,000 feet to 60% at 40,000. The frequency of upward motion PIREPS is significantly greater than frequency of downward motion PIREPS. Contrails occur more frequently at lower temperatures, regardless of the vertical motion, but they occur more frequently at the same temperature when there is upward motion. Above 40,000 feet, contrail frequency decreases from 100% between 410 and 440 feet to about 30% above 65,000 feet. Contrails occur 92% of the time when temperatures are -70° C or less.

5.1.3 Contrail frequency using HIRAS data between FL 250 and 340 was similar to the frequency using PIREP data. Z statistics indicate that the differences in frequency of occurrence between upward and downward vertical motion are generally not significant. Between 350 and 400 feet, contrail frequency was higher for downward than for upward motion, but Z statistics show the difference to be insignificant.

5.1.4 ETACFCST showed the most skill in both dependent and independent tests using PIREP or HIRAS data. Below 40,000 ft, ETACFCST had a significantly higher probability of detection (POD) than either Appleman or SAC/DOW, but the false alarm rate (FAR) was also higher. Appleman was slightly better than SAC/DOW in skill, POD, and FAR. Above 40,000 feet, ETACFCST had better skill, percent correct, and FAR than the other curves, but the POD was about 20% lower than Appleman or SAC/DOW.

5.1.5 Performing several discriminant analyses (every 5,000 feet) between FL 200 and 400 using HIRAS data offered some improvement over the "single" discriminant analysis method, especially when only downward motion data was considered. In general, skill, POD, COR, and FAR improve with increasing flight level. However, we do not recommend these curves be used due to data limitations in their development.

5.2 Recommendations for Operational Use. Use USAFETAC's empirical technique (discriminant analysis) in combination with SAC/DOW's engine classification technique to forecast contrails; specifically,

- For aircraft with non-bypass engines flying at/below 40,000 ft (KC-135A and B-52G), use the discriminant equation provided in Appendix D, Table D-5.

- For aircraft with non-bypass engines flying *above* 40,000 ft (U-2), use the discriminant equation provided in Table D-4.
- For aircraft with high-bypass engines flying *at/below* 40,000 ft (KC-135R) use the discriminant equation provided in Table D-2.
- There is not enough data to use empirical techniques below 25,000 ft.

5.3. Recommendations for Future Algorithm Development. An independent dataset (to test the engine-specific contrail algorithms) should be obtained. Also, recommend that AWS/XTX arrange for the collection of more engine-specific data with ACC/DOW and AMC/DOW. The new data should be used to refine existing algorithms.

APPENDIX A

TABLE A-1. Statistics for PIREP temperature and upward/downward vertical motion data using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data at/below 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index, COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.17	0.23	0.18	78.0	18.0	18.8
APPLEMAN	0.26	0.33	0.27	79.5	23.1	29.4
ETACFCST	0.42	0.34	0.39	68.4	56.3	77.0

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.13	0.18	0.15	73.9	23.1	15.4
APPLEMAN	0.23	0.28	0.25	75.6	27.9	27.1
ETACFCST	0.43	0.36	0.42	68.6	52.2	78.8

TABLE A-2. Statistics for PIREP temperature and upward vertical motion data using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data at/below 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.13	0.16	0.14	69.3	13.5	14.1
APPLEMAN	0.21	0.25	0.23	71.8	16.1	23.6
ETACFCST	0.48	0.45	0.50	72.8	41.8	78.1

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.10	0.11	0.11	59.1	15.4	11.6
APPLEMAN	0.19	0.20	0.21	63.1	11.1	21.1
ETACFCST	0.38	0.37	0.54	67.6	39.8	83.7

TABLE A-3. Statistics for PIREP temperature and downward vertical motion data using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data at/below 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.26	0.35	0.26	86.0	22.8	28.2
APPLEMAN	0.38	0.45	0.35	86.6	30.6	41.7
ETACFCST	0.45	0.30	0.31	68.8	66.6	78.7

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.23	0.29	0.24	78.7	27.0	26.2
APPLEMAN	0.36	0.40	0.37	79.2	37.3	45.6
ETACFCST	0.38	0.43	0.36	59.9	62.5	87.2

TABLE A-4. Statistics for PIREP temperature data (no vertical motion above 40,000 feet) using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data above 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.00	0.00	0.61	60.6	39.4	100.
APPLEMAN	0.47	0.50	0.71	77.4	23.8	91.4
ETACFCST	0.60	0.67	0.67	79.1	11.6	75.4

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.00	0.00	0.71	71.4	28.6	100.
APPLEMAN	0.41	0.44	0.75	78.8	17.8	82.2
ETACFCST	0.51	0.44	0.65	73.2	10.1	70.3

TABLE A-5. Statistics for HIRAS temperature and upward/downward vertical motion data using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data at/below 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.16	0.22	0.17	77.5	22.1	18.1
APPLEMAN	0.25	0.31	0.26	79.1	23.7	27.8
ETACFCST	0.41	0.33	0.38	68.5	56.3	75.1

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.17	0.17	0.15	73.7	25.4	15.4
APPLEMAN	0.26	0.26	0.23	75.6	24.0	24.3
ETACFCST	0.45	0.38	0.43	69.8	51.0	78.8

TABLE A-6. Statistics for HIRAS temperature and upward vertical motion data using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data at/below 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.15	0.21	0.16	76.7	20.9	17.0
APPLEMAN	0.23	0.29	0.24	78.3	21.7	25.7
ETACFCST	0.38	0.32	0.37	68.0	56.1	71.5

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.13	0.13	0.11	72.8	24.0	11.6
APPLEMAN	0.22	0.24	0.20	75.5	15.0	20.7
ETACFCST	0.46	0.40	0.44	71.0	49.4	78.1

TABLE A-7. Statistics for HIRAS temperature and downward vertical motion data using SAC/DOW, Appleman, and USAFETAC contrail prediction curves. Dependent and independent data at/below 40,000 feet. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.17	0.23	0.18	78.2	23.1	19.1
APPLEMAN	0.26	0.33	0.27	79.8	25.6	30.0
ETACFCST	0.45	0.35	0.39	69.3	56.2	78.7

INDEPENDENT						
PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
SAC/DOW	0.16	0.21	0.18	74.6	26.2	19.3
APPLEMAN	0.23	0.28	0.25	75.6	29.7	28.0
ETACFCST	0.47	0.39	0.44	70.4	50.6	80.1

APPENDIX B

TABLE B-1. Discriminant equations and resulting statistics using HIRAS temperature and upward/downward vertical motion data. A different curve is determined for each 5,000 ft (or 6,000 ft) increment between 20,000 and 40,000 ft. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DISCRIMINANT EQUATIONS

200/240	TCRIT = -51.23 + 0.1196 (FL)
250/290	TCRIT = -31.67 - 0.0185 (FL)
300/340	TCRIT = -27.01 - 0.0563 (FL)
350/400	TCRIT = -31.20 - 0.0539 (FL)

DEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.24	0.06	0.08	64.4	91.4	59.3
250/290	0.31	0.23	0.29	65.5	66.2	65.8
300/340	0.36	0.33	0.42	67.7	49.0	69.2
350/400	0.42	0.41	0.61	71.3	21.5	72.9

INDEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.17	0.07	0.12	65.4	87.0	50.0
250/290	0.34	0.41	0.33	66.8	60.8	67.9
300/340	0.41	0.38	0.47	69.2	44.3	75.5
350/400	0.29	0.27	0.62	69.2	20.0	75.7

TABLE B-2. Discriminant equations and resulting statistics using HIRAS temperature and upward vertical motion data. A different curve is determined for each 5,000 ft (or 6,000 ft) increment between 20,000 and 40,000 ft. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percentage correct; FAR--False alarm rate; and POD--Probability of detection.

DISCRIMINANT EQUATIONS

200/240	TCRIT = -50.06 + 0.1166 (FL)
250/290	TCRIT = -33.47 - 0.0097 (FL)
300/340	TCRIT = -33.02 - 0.0352 (FL)
350/400	TCRIT = -40.09 - 0.0302 (FL)

DEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.08	0.02	0.06	60.9	93.3	46.2
250/290	0.32	0.26	0.32	67.1	61.6	64.3
300/340	0.33	0.30	0.39	66.7	50.6	66.2
350/400	0.30	0.29	0.52	65.1	29.1	66.1

INDEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.21	0.08	0.04	61.1	86.4	60.0
250/290	0.30	0.25	0.32	67.2	60.0	60.0
300/340	0.43	0.40	0.47	70.4	44.1	75.6
350/400	0.21	0.21	0.55	63.0	29.4	70.6

TABLE B-3. Discriminant equations and resulting statistics using HIRAS temperature and downward vertical motion data. A different curve is determined for each 5,000 ft (or 6,000 ft) increment between 20,000 and 40,000 ft. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DISCRIMINANT EQUATIONS

200/240	TCRIT = -51.00 + 0.1158 (FL)
250/290	TCRIT = -28.62 - 0.0320 (FL)
300/340	TCRIT = -20.37 - 0.0795 (FL)
350/400	TCRIT = -27.26 - 0.0678 (FL)

DEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.40	0.11	0.10	68.5	89.3	71.4
250/290	0.32	0.22	0.27	65.2	69.0	67.9
300/340	0.39	0.36	0.43	68.7	47.6	71.9
350/400	0.50	0.49	0.67	75.6	16.2	76.5

INDEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.16	0.08	0.12	70.9	86.4	42.9
250/290	0.41	0.30	0.35	65.9	61.7	78.9
300/340	0.32	0.30	0.43	65.1	47.2	69.1
350/400	0.40	0.24	0.73	72.0	11.1	80.0

APPENDIX C

TABLE C-1. Statistics for HIRAS temperature and upward/downward vertical motion data using Equation 17. Data are placed in 5,000 ft (or 6,000 ft) increments as shown. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.22	0.24	0.16	92.7	70.8	25.9
250/290	0.35	0.29	0.31	71.6	61.0	60.8
300/340	0.27	0.21	0.39	56.7	57.8	83.0
350/400	0.14	0.16	0.63	65.7	35.6	97.1

INDEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.03	0.31	0.21	91.7	40.0	33.3
250/290	0.38	0.34	0.36	72.2	55.4	63.4
300/340	0.32	0.27	0.45	60.0	52.6	89.0
350/400	0.13	0.17	0.74	75.0	26.0	100.

TABLE C-2. Statistics for HIRAS temperature and upward vertical motion data using Equation 18. Data are placed in 5,000 ft (or 6,000 ft) increments as shown. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.24	0.20	0.14	89.7	79.0	30.8
250/290	0.35	0.32	0.34	72.9	55.5	57.7
300/340	0.24	0.20	0.37	56.5	58.6	77.8
350/400	0.15	0.17	0.60	63.1	38.5	94.9

INDEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.60	0.73	0.60	96.3	0.00	60.0
250/290	0.34	0.32	0.34	72.7	53.5	55.0
300/340	0.40	0.32	0.47	63.5	51.0	91.5
350/400	0.10	0.13	0.65	66.7	34.6	100.

TABLE C-3. Statistics for HIRAS temperature and downward vertical motion data using Equation 19. Data are placed in 5,000 ft (or 6,000 ft) increments as shown. VDS--V discriminant score; HSS--Heidke skill score; CSI--Critical skill index; COR--percent correct; FAR--False alarm rate; and POD--Probability of detection.

DEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.20	0.24	0.16	94.2	62.5	21.4
250/290	0.38	0.31	0.31	73.5	62.2	61.5
300/340	0.27	0.21	0.40	55.4	57.9	88.0
350/400	0.12	0.14	0.66	67.7	33.3	98.8

INDEPENDENT

PREDICTION CURVE	VDS	HSS	CSI	COR	FAR	POD
200/240	0.00	0.00	0.00	88.6	100.	0.00
250/290	0.48	0.41	0.40	75.7	52.0	71.2
300/340	0.25	0.21	0.43	55.8	54.4	88.9
350/400	0.20	0.29	0.83	84.0	16.7	100.

APPENDIX D

TABLE D-1. Comparison of the ETAC empirical and SAC/DOW theoretical contrail prediction algorithms using B-52G data (340 observations). VDS--Discriminant V Skill Score; FAR--False Alarm Rate; POD--Probability of Detection. OCCUR: Forecast occurrence of contrails. NON-OCCUR: Forecast non-occurrence of contrails. Also shown is the ETAC discriminant equation (TCRIT is the critical temperature for contrail formation in degrees celsius; FL is flight level in hundreds of feet (i.e., 200 = 20,000 ft)).

B-52G NON BY-PASS ENGINE

	ETAC	SAC/DOW
VDS	0.55	0.37
OCCUR		
POD	79	40
FAR	30	5
NON-OCCUR		
POD	77	98
FAR	16	43
TCRIT = 3.47 - 0.152 (FL)		

TABLE D-2. Comparison of the ETAC empirical and SAC/DOW theoretical contrail prediction algorithms using KC-135R data (332 observations). VDS--Discriminant V Skill Score; FAR--False Alarm Rate; POD--Probability of Detection. OCCUR: Forecast occurrence of contrails. NON-OCCUR: Forecast non-occurrence of contrails. Also shown is the ETAC discriminant equation (TCRIT is the critical temperature for contrail formation in degrees celsius; FL is flight level in hundreds of feet (i.e., 200 = 20,000 ft)).

KC-135R HIGH BY-PASS ENGINE

	ETAC	SAC/DOW
VDS	0.58	0.53
OCCUR		
POD	83	71
FAR	28	22
NON-OCCUR		
POD	75	82
FAR	15	24
TCRIT = -9.45 - 0.105 (FL)		

TABLE D-3. Comparison of the ETAC empirical and SAC/DOW theoretical contrail prediction algorithms using KC-135A data (322 observations). VDS--Discriminant V Skill Score; FAR--False Alarm Rate; POD--Probability of Detection. OCCUR: Forecast occurrence of contrails. NON-OCCUR: Forecast non-occurrence of contrails. Also shown is the ETAC discriminant equation (TCRIT is the critical temperature for contrail formation in degrees celsius; FL is flight level in hundreds of feet (i.e., 200 = 20,000 ft)).

KC135-A NON BY-PASS ENGINE

	ETAC	SAC/DOW
VDS	0.48	0.46
OCCUR		
POD	79	61
FAR	28	18
NON-OCCUR		
POD	69	85
FAR	24	34

$$\text{TCRIT} = -6.87 - 0.121 \text{ (FL)}$$

TABLE D-4. Comparison of the ETAC empirical and SAC/DOW theoretical contrail prediction algorithms using U-2 data (1022 observations). VDS--Discriminant V Skill Score; FAR--False Alarm Rate; POD--Probability of Detection. OCCUR: Forecast occurrence of contrails. NON-OCCUR: Forecast non-occurrence of contrails. Also shown is the ETAC discriminant equation (TCRIT is the critical temperature for contrail formation in degrees celsius; FL is flight level in hundreds of feet (i.e., 200 = 20,000 ft)).

U-2 NON BY-PASS ENGINE

	ETAC	SAC/DOW
VDS	0.60	0.62
OCCUR		
POD	79	75
FAR	12	11
NON-OCCUR		
POD	70	86
FAR	28	31

$$\text{TCRIT} = -31.6 - 0.057 \text{ (FL)}$$

TABLE D-5. Comparison of the ETAC empirical and SAC/DOW theoretical contrail prediction algorithms using KC-135A and B-52G data (non by-pass engine; at/below 40,000 ft). VDS--Discriminant V Skill Score; FAR--False Alarm Rate; POD--Probability of Detection. OCCUR: Forecast occurrence of contrails. NON-OCCUR: Forecast non-occurrence of contrails. Also shown is the ETAC discriminant equation (TCRIT is the critical temperature for contrail formation in degrees celsius; FL is flight level in hundreds of feet (i.e., 200 = 20,000 ft)).

B-52G and KC-135A, NON BY-PASS ENGINE

	ETAC	SAC/DOW
VDS	0.51	N/A
OCCUR		
POD	80	
FAR	30	
NON-OCCUR		
POD	81	
FAR	19	
TCRIT =	-1.61 - 0.137 (FL)	

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ACRINABS

AFGWC	Air Force Global Weather Central
AWAPS	Advanced Weather Analysis and Prediction System
a_1	discriminant weight used in discriminant analysis
a_2	discriminant weight used in discriminant analysis
COR	percent correct
CSI	Critical Skill Index
DA	Discriminant Analysis
$d_x u$	difference of u-comp horizontal wind in ms^{-1}
$d_x v$	difference of v-comp horizontal wind in ms^{-1}
e	exponential
ETACFCST	USAFETAC algorithm for forecasting contrails
FAR	False Alarm Rate
FL	Flight Level in meters
FLTLVL	flight level in meters
FCST	forecast
g	gravity in ms^{-2}
HIRAS	High Resolution Analysis System
HSS	Heidke Skill Score
m	meters
mb	millibars
ms^{-1}	meters per second
N	number of observations
NGM	Nested Gridded Model
nm	nautical miles
OBS	observed
P	distance in meters
p	pressure in millibars
p_i	pressure in millibars at level i
p_{i+1}	pressure in millibars at level $i+1$
PIBAL	PIBAL observation
PIREP	Pilot Report
POD	Probability of Detection
PVAL	p-value
QC	quality control
R	dry gas constant
ϵ_k	density in kgm^{-3} at level k
ϵ_{k-1}	density in kgm^{-3} at level $k-1$
RAOB	Radiosonde observation
RH	relative humidity
S	interpolated distance in meters
SAC	Strategic Air Command
SAC/DO	Strategic Air Command, Director of Operations
SAC/DOW	Strategic Air Command, Director of Weather
T	Temperature in $^{\circ}\text{C}$ at required point or PIREP point
T_i	Temperature in $^{\circ}\text{C}$ at grid point i or at pressure p_i
T_{i+1}	Temperature in $^{\circ}\text{C}$ at grid point $i+1$ or at pressure p_{i+1}

T_p	Temperature in °C at latitude/longitude location of PIREP at standard levels above/below each PIREP
T_{S1}	Temperature in °C at point S1
T_{S2}	Temperature in °C at point S2
TCRIT	Critical temperature (°C) for formation of contrails
TROPFCST	Appleman algorithm for forecasting contrails
USAFETAC	USAF Environmental Technical Applications Center
VDS	Discriminant V-score
w_k	vertical velocity in ms^{-1} half a level above standard level
w_{k-1}	vertical velocity in ms^{-1} half a level below standard level
Z	discriminant score
Z_M	flight level in feet
Z_m	flight level in meters

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